

MS5637-02BA03

Low Voltage Barometric Pressure Sensor

SPECIFICATIONS

- QFN package 3 x 3 x 0.9 mm³
- High-resolution module, 13 cm
- Supply voltage: 1.5 to 3.6 V
- Fast conversion down to 0.5 ms
- Low power, 0.6 μA (standby ≤ 0.1 μA at 25°C)
- Integrated digital pressure sensor (24 bit ΔΣ ADC)
- Operating range: 300 to 1200 mbar, -40 to +85 °C
- I²C interface
- No external components (internal oscillator)

The MS5637 is an ultra-compact micro altimeter. It is optimized for altimeter and barometer applications in Smart-phones and Tablet PCs. The altitude resolution at sea level is 13 cm of air. The sensor module includes a high-linearity pressure sensor and an ultra-low power 24 bit $\Delta\Sigma$ ADC with internal factory-calibrated coefficients. It provides a precise digital 24-bit pressure and temperature value and different operation modes that allow the user to optimize for conversion speed and current consumption. A high-resolution temperature output allows the implementation of an altimeter/thermometer function without any additional sensor. The MS5637 can be interfaced to any microcontroller with I²C-bus interface. The communication protocol is simple, without the need of programming internal registers in the device. Small dimensions of 3 x 3 x 0.9 mm³ allow the integration in mobile devices. This new sensor module generation is based on leading MEMS technology and latest benefits from MEAS Switzerland proven experience and know-how in high volume manufacturing of altimeter modules, which has been widely used for over a decade. The sensing principle employed leads to very low hysteresis and high stability of both pressure and temperature signal.

FEATURES

FIELD OF APPLICATION

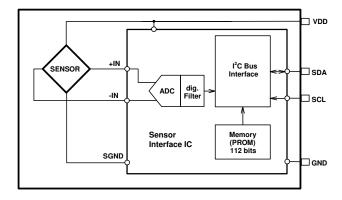
Smart-phones
Tablet PCs

Personal navigation devices

TECHNICAL DATA

Sensor Performances (VDE	o = 3 V)				
Pressure	Min	Тур	Max	Unit	
Maximum Range	10		2000 mbai		
ADC		24		bit	
Resolution (1)	0.11 / 0.	mbar			
Error band at 25°C, 300 to 1200 mbar	-2		+2	mbar	
Error band, -20°C to + 85°C 300 to 1200 mbar (2)	-4		+4	mbar	
Response time (1)		1.1 / 2.1 .22 / 16.4		ms	
Long term stability		±1		mbar/yr	
Temperature	Min	Тур	Max	Unit	
Range	-40		+85	°C	
Resolution		<0.01		°C	
Accuracy at 25°C	-1		+1	°C	
Notes: (1) Oversampling Ratio: 25 (2) With auto-zero at one			48 / 409	6 / 8192	

FUNCTIONAL BLOCK DIAGRAM



PERFORMANCE SPECIFICATIONS

ABSOLUTE MAXIMUM RATINGS

Parameter	Symbol	Conditions	Min.	Тур.	Max.	Unit
Supply voltage	V_{DD}		-0.3		+3.6	V
Storage temperature	Ts		-20		+85	°C
Overpressure	P _{max}			6		bar
Maximum Soldering Temperature	T _{max}	40 sec max			250	°C
ESD rating		Human Body Model	-2		+2	kV
Latch up		JEDEC standard No 78	-100		+100	mA

ELECTRICAL CHARACTERISTICS

Parameter	Symbol	Conditions		Min.	Тур.	Max.	Unit
Operating Supply voltage	V_{DD}			1.5	3.0	3.6	V
Operating Temperature	Т			-40	+25	+85	°C
		OSR	8192		20.09		
			4096		10.05		
Supply current	I _{DD}		2048		5.02		
(1 sample per sec.)			1024		2.51		μΑ
			512		1.26		
			256		0.63		
Peak supply current		during convers	sion		1.25		mA
Standby supply current		at 25°C (V _{DD} =	3.0 V)		0.01	0.1	μΑ
VDD Capacitor		from VDD to G	iND	100	470		nF

ANALOG DIGITAL CONVERTER (ADC)

Parameter	Symbol	Conditions		Min.	Тур.	Max.	Unit
Output Word					24		bit
		OSR	8192		16.44		
			4096		8.22		
Conversion time			2048		4.13		mo
Conversion time	lc		1024		2.08		ms
			512		1.06		
			256		0.54		

PERFORMANCE SPECIFICATIONS (CONTINUED)

PRESSURE OUTPUT CHARACTERISTICS (V_{DD} = 3.0 V, T = 25 °C UNLESS OTHERWISE NOTED)

Parameter	Condition	ns	Min.	Тур.	Max.	Unit
Operating Pressure Range	Prange		300		1200	mbar
Extended Pressure Range	P _{ext}	Linear Range of ADC	10		2000	mbar
Relative Accuracy, autozero at one pressure point (1)	700100	0 mbar at 25°C		±0.1		mbar
Absolute Accuracy, no autozero) mbar at 25°C)mbar, -2085°C	-2 -4		+2 +4	mbar
Resolution RMS	OSR	8192 4096 2048 1024 512 256		0.016 0.021 0.028 0.039 0.062 0.11		mbar
Maximum error with supply voltage	V _{DD} = 1.5	V 3.6 V		±0.5		mbar
Long-term stability				±1		mbar/yr
Reflow soldering impact	(See appl	EC J-STD-020C lication note AN808 neas-spec.com)		-1		mbar
Recovering time after reflow (2)				3		days

⁽¹⁾ Characterized value performed on qualification devices

TEMPERATURE OUTPUT CHARACTERISTICS (V_{DD} = 3 V, T = 25°C UNLESS OTHERWISE NOTED)

Parameter	Conditions		Min.	Тур.	Max.	Unit
Abaquita Agguragy	at 25°C	at 25°C			+1	°C
Absolute Accuracy	-2085°C		-2		+2	
Maximum error with supply voltage	V _{DD} = 1.5 V 3.6 V			±0.3		°C
	OSR	8192		0.002		
		4096		0.003		
Resolution RMS		2048				°C
Resolution Rivis		1024		0.006		
		512		0.009		
		256		0.012		

⁽²⁾ Recovering time at least 66% of the reflow impact

PERFORMANCE SPECIFICATIONS (CONTINUED)

DIGITAL INPUTS (SDA, SCL)

Parameter	Symbol	Conditions	Min.	Тур.	Max.	Unit
Serial data clock	SCL				400	kHz
Input high voltage	ViH		80% V _{DD}		100% V _{DD}	V
Input low voltage	VIL		0% V _{DD}		20% V _{DD}	V
Input leakage current	I _{leak}	T = 25 °C			0.1	μΑ
Input capacitance	Cin			6		pF

DIGITAL OUTPUTS (SDA)

Parameter	Symbol	Conditions	Min.	Тур.	Max.	Unit
Output high voltage	V_{OH}	I _{source} = 1 mA	80% V _{DD}		100% V _{DD}	V
Output low voltage	Vol	I _{sink} = 1 mA	0% V _{DD}		20% V _{DD}	V
Load capacitance	CLOAD			16		pF

FUNCTIONAL DESCRIPTION

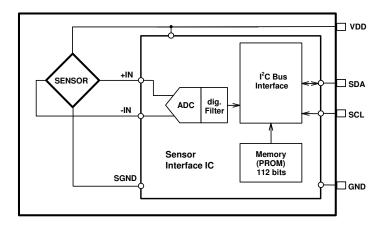


Figure 1: Block diagram

GENERAL

The MS5637 consists of a piezo-resistive sensor and a sensor interface integrated circuit. The main function of the MS5637 is to convert the uncompensated analogue output voltage from the piezo-resistive pressure sensor to a 24-bit digital value, as well as providing a 24-bit digital value for the temperature of the sensor.

FACTORY CALIBRATION

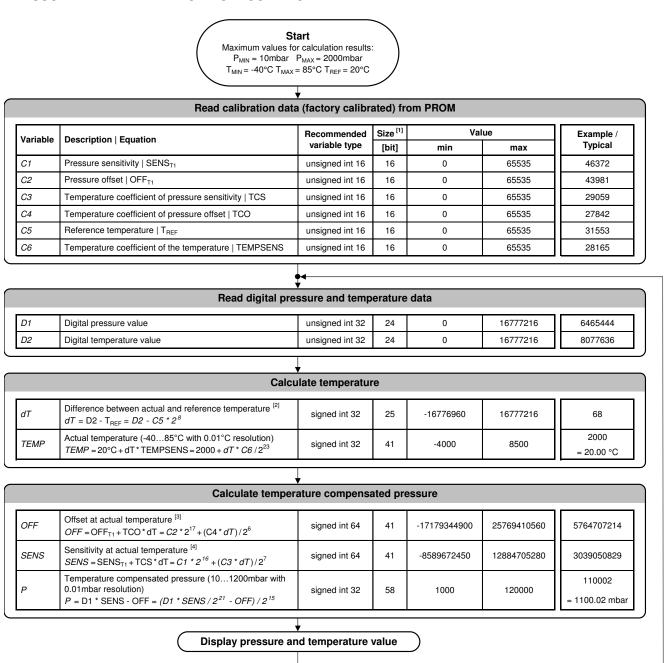
Every module is individually factory calibrated at two temperatures and two pressures. As a result, 6 coefficients necessary to compensate for process variations and temperature variations are calculated and stored in the 112-bit PROM of each module. These bits (partitioned into 6 coefficients) must be read by the microcontroller software and used in the program converting D1 and D2 into compensated pressure and temperature values.

SERIAL I2C INTERFACE

The external microcontroller clocks in the data through the input SCL (Serial CLock) and SDA (Serial DAta). The sensor responds on the same pin SDA which is bidirectional for the I²C bus interface. So this interface type uses only 2 signal lines and does not require a chip select.

Module reference	Mode	Pins used
MS563702BA03	I ² C	SDA. SCL

PRESSURE AND TEMPERATURE CALCULATION



Notes

[1] Maximal size of intermediate result during evaluation of variable

[2] min and max have to be defined
[3] min and max have to be defined
[4] min and max have to be defined

Figure 2: Flow chart for pressure and temperature reading and software compensation.

SECOND ORDER TEMPERATURE COMPENSATION

In order to obtain best accuracy over temperature range, particularly at low temperature, it is recommended to compensate the non-linearity over the temperature. This can be achieved by correcting the calculated temperature, offset and sensitivity by a second-order correction factor. The second-order factors are calculated as follows:

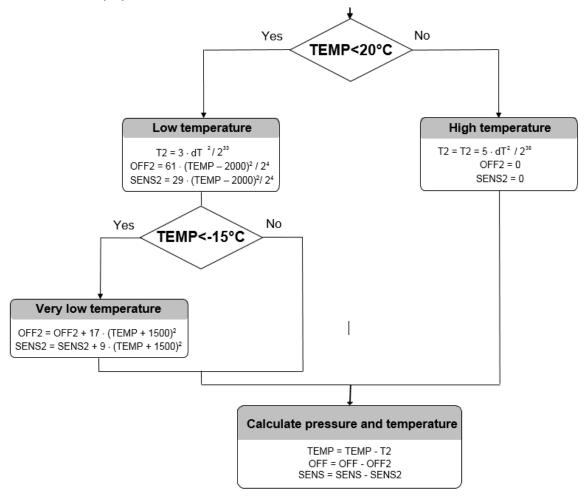


Figure 3: Flow chart for pressure and temperature to the optimum accuracy.

I²C INTERFACE

COMMANDS

The MS5637 has only five basic commands:

- 1. Reset
- 2. Read PROM (112 bit of calibration words)
- 3. D1 conversion
- 4. D2 conversion
- 5. Read ADC result (24 bit pressure / temperature)

Each I^2C communication message starts with the start condition and it is ended with the stop condition. The MS5637 address is 1110110x (write: x=0, read: x=1).

Size of each command is 1 byte (8 bits) as described in the table below. After ADC read commands, the device will return 24 bit result and after the PROM read 16 bit results. The address of the PROM is embedded inside of the PROM read command using the a2, a1 and a0 bits.

	Com	mand	byte						hex value
Bit number	0	1	2	3	4	5	6	7	
Bit name	PRO M	CO NV	-	Тур	Ad2/ Os2	Ad1/ Os1	Ad0/ Os0	Stop	
Command									
Reset	0	0	0	1	1	1	1	0	0x1E
Convert D1 (OSR=256)	0	1	0	0	0	0	0	0	0x40
Convert D1 (OSR=512)	0	1	0	0	0	0	1	0	0x42
Convert D1 (OSR=1024)	0	1	0	0	0	1	0	0	0x44
Convert D1 (OSR=2048)	0	1	0	0	0	1	1	0	0x46
Convert D1 (OSR=4096)	0	1	0	0	1	0	0	0	0x48
Convert D1 (OSR=8192)	0	1	0	0	1	0	1	0	0x4A
Convert D2 (OSR=256)	0	1	0	1	0	0	0	0	0x50
Convert D2 (OSR=512)	0	1	0	1	0	0	1	0	0x52
Convert D2 (OSR=1024)	0	1	0	1	0	1	0	0	0x54
Convert D2 (OSR=2048)	0	1	0	1	0	1	1	0	0x56
Convert D2 (OSR=4096)	0	1	0	1	1	0	0	0	0x58
Convert D2 (OSR=8192)	0	1	0	1	1	0	1	0	0x5A
ADC Read	0	0	0	0	0	0	0	0	0x00
PROM Read	1	0	1	0	Ad2	Ad1	Ad0	0	0xA0 to 0xAE

Figure 4: Command structure

RESET SEQUENCE

The Reset sequence shall be sent once after power-on to make sure that the calibration PROM gets loaded into the internal register. It can be also used to reset the device PROM from an unknown condition.

The reset can be sent at any time. In the event that there is not a successful power on reset this may be caused by the SDA being blocked by the module in the acknowledge state. The only way to get the MS5637 to function is to send several SCLs followed by a reset sequence or to repeat power on reset.

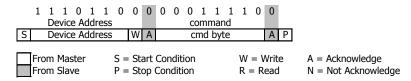


Figure 5: I2C Reset Command

PROM READ SEQUENCE

The read command for PROM shall be executed once after reset by the user to read the content of the calibration PROM and to calculate the calibration coefficients. There are in total 7 addresses resulting in a total memory of 112 bit. Addresses contains factory data and the setup, calibration coefficients, the serial code and CRC. The command sequence is 8 bits long with a 16 bit result which is clocked with the MSB first. The PROM Read command consists of two parts. First command sets up the system into PROM read mode. The second part gets the data from the system.

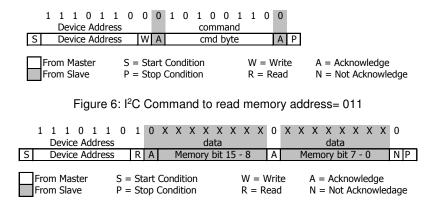


Figure 7: I²C answer from MS5637

CONVERSION SEQUENCE

The conversion command is used to initiate uncompensated pressure (D1) or uncompensated temperature (D2) conversion. After the conversion, using ADC read command the result is clocked out with the MSB first. If the conversion is not executed before the ADC read command, or the ADC read command is repeated, it will give 0 as the output result. If the ADC read command is sent during conversion the result will be 0, the conversion will not stop and the final result will be wrong. Conversion sequence sent during the already started conversion process will yield incorrect result as well. A conversion can be started by sending the command to MS5637. When command is sent to the system it stays busy until conversion is done. When conversion is finished the data can be accessed by sending a Read command, when an acknowledge is sent from the MS5637, 24 SCL cycles may be sent to receive all result bits. Every 8 bits the system waits for an acknowledge signal.

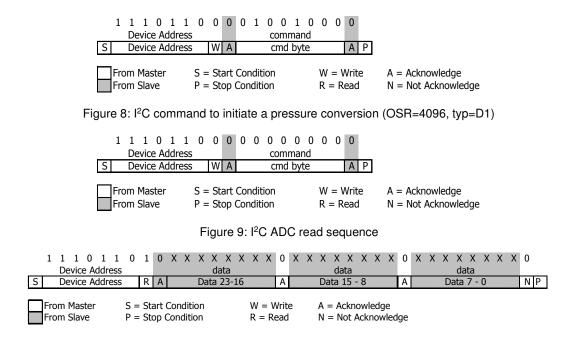


Figure 10: I²C answer from MS5637

CYCLIC REDUNDANCY CHECK (CRC)

MS5637 contains a PROM memory with 112-Bit. A 4-bit CRC has been implemented to check the data validity in memory. The C code example below describes the CRC calculation which is stored on DB12 to DB15 in the first PROM word.

A d d	D B 1 5	D B 1 4	D B 1 3	D B 1 2	D B 1	D B 1 0	D B 9	D B 8	D B 7	D B 6	D B 5	D B 4	D B 3	D B 2	D B 1	D B 0
0		CRC Factory defined														
1		C1														
2								С	2							
3								С	3							
4		C4														
5		C5														
6								С								

Figure 11: Memory PROM mapping

C Code example for CRC-4 calculation:

```
unsigned char crc4(unsigned int n_prom[])
                                                                      // n_prom defined as 8x unsigned int (n_prom[8])
                                                                      // simple counter
int cnt;
unsigned int n_rem=0;
                                                                      // crc reminder
unsigned char n_bit;
          n_prom[0]=((n_prom[0]) \& 0x0FFF);
                                                                      // CRC byte is replaced by 0
          n_prom[7]=0;
                                                                      // Subsidiary value, set to 0
          for (cnt = 0; cnt < 16; cnt++)
                                                                      // operation is performed on bytes
                                                                      // choose LSB or MSB
                    if (cnt%2==1)
                                        n_rem ^= (unsigned short) ((n_prom[cnt>>1]) & 0x00FF);
                                        n_rem ^= (unsigned short) (n_prom[cnt>>1]>>8);
                    for (n_bit = 8; n_bit > 0; n_bit = 0)
                              if (n_rem & (0x8000))
                                                            n_rem = (n_rem << 1) ^0x3000;
                              else
                                                            n_rem = (n_rem << 1);
          n_rem = ((n_rem >> 12) \& 0x000F);
                                                                      // final 4-bit reminder is CRC code
          return (n_rem ^ 0x00);
}
```

APPLICATION CIRCUIT

The MS5637 is a circuit that can be used in conjunction with a microcontroller in mobile altimeter applications.

I²C protocol communication

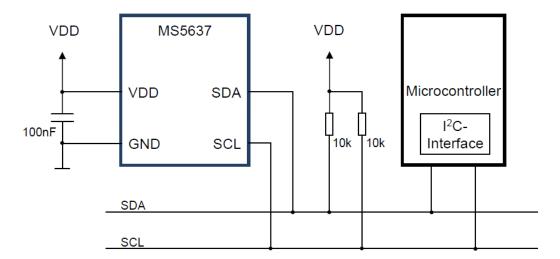
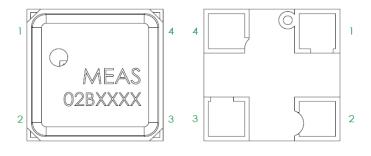


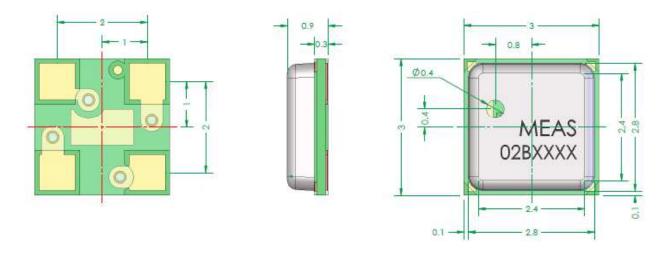
Figure 12: Typical application circuit

PIN CONFIGURATION

Pin	Name	Туре	Function
1	VDD	Р	Positive supply voltage
2	SDA	I/O	I ² C data
3	SCL	I	I ² C clock
4	GND	I	Ground



DEVICE PACKAGE OUTLINE



Notes: (1) Dimensions in mm

(2) General tolerance: ±0.1

Figure 13: MS5637 package outline

RECOMMENDED PAD LAYOUT

Pad layout for bottom side of the MS5637 soldered onto printed circuit board.

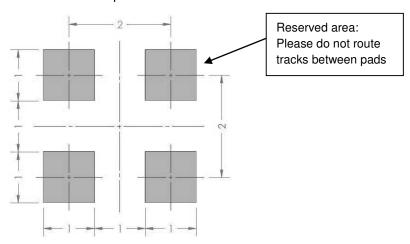
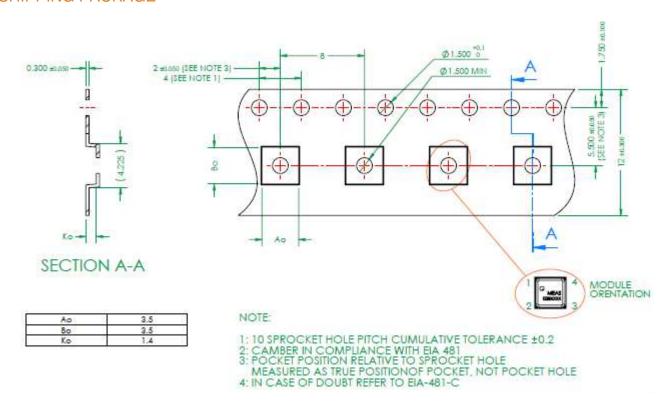


Figure 14: MS5637 pad layout

SHIPPING PACKAGE



MOUNTING AND ASSEMBLY CONSIDERATIONS

SOLDERING

Please refer to the application note AN808 available on our website for all soldering issues.

MOUNTING

The MS5637 can be placed with automatic Pick & Place equipment using vacuum nozzles. It will not be damaged by the vacuum. Due to the low stress assembly the sensor does not show pressure hysteresis effects. It is important to solder all contact pads.

CONNECTION TO PCB

The package outline of the module allows the use of a flexible PCB for interconnection. This can be important for applications in watches and other special devices.

CLEANING

The MS5637 has been manufactured under clean-room conditions. It is therefore recommended to assemble the sensor under class 10'000 or better conditions. Should this not be possible, it is recommended to protect the sensor opening during assembly from entering particles and dust. To avoid cleaning of the PCB, solder paste of type "noclean" shall be used. Cleaning might damage the sensor!

ESD PRECAUTIONS

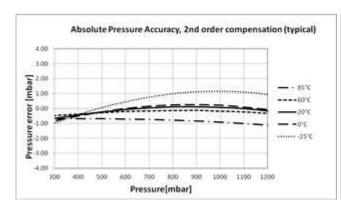
The electrical contact pads are protected against ESD up to 2 kV HBM (human body model). It is therefore essential to ground machines and personnel properly during assembly and handling of the device. The MS5637 is shipped in antistatic transport boxes. Any test adapters or production transport boxes used during the assembly of the sensor shall be of an equivalent antistatic material.

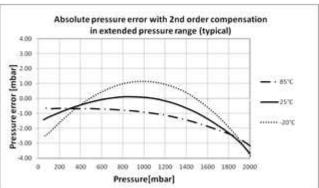
DECOUPLING CAPACITOR

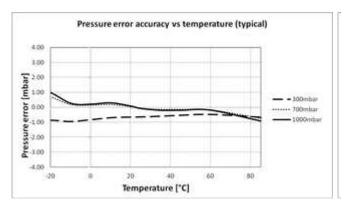
Particular care must be taken when connecting the device to the power supply. A 100nF minimum ceramic capacitor must be placed as close as possible to the MS5637 VDD pin. This capacitor will stabilize the power supply during data conversion and thus, provide the highest possible accuracy.

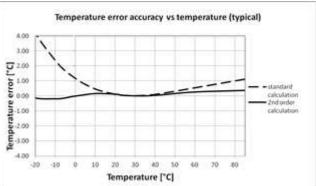
TYPICAL PERFORMANCE CHARACTERISTICS

PRESSURE AND TEMPERATURE ERROR VERSUS PRESSURE AND TEMPERATURE (TYPICAL VALUES)

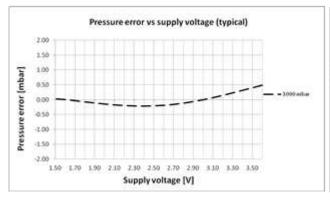


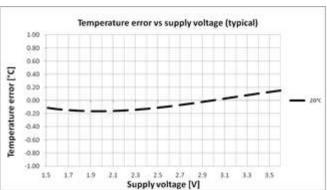






PRESSURE AND TEMPERATURE ERROR VERSUS POWER SUPPLY (TYPICAL VALUES)





ORDERING INFORMATION

Part Number / Art. Number	Product	Delivery Form
MS563702BA03-50	Micro Altimeter Module 3x3mm	Tape & Reel

NORTH AMERICA

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